

# تقدم لجنة ElCoM الاكاديمية

# تلخيص لمادة:

# الهوائيات وانتشار الموجات

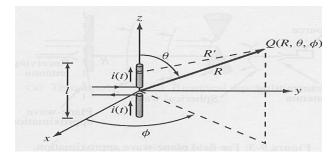


#### Antenna Summary Chapter 9

For Reactive Near Field Region  $R = .62\sqrt{L^3/\lambda}$  & For Radiating Near Field Region  $R = 2L^2/\lambda$ 

#### 9-1 The Short Dipole

For A short dipole, also called a *Hertzian dipole*. l should not exceed  $\lambda/50$ .



Short Dipole

$$\widetilde{A}_{R} = \frac{\mu_{0}I_{0}l}{4\pi}\cos\theta\left(\frac{e^{-jkR}}{R}\right),$$
$$\widetilde{A}_{\theta} = -\frac{\mu_{0}I_{0}l}{4\pi}\sin\theta\left(\frac{e^{-jkR}}{R}\right)$$
$$\widetilde{A}_{\phi} = 0.$$

$$\widetilde{H}_{\phi} = \frac{I_0 l k^2}{4\pi} e^{-jkR} \left[ \frac{j}{kR} + \frac{1}{(kR)^2} \right] \sin \theta \qquad (9.8a)$$

$$\widetilde{E}_R = \frac{2I_0 l k^2}{4\pi} \eta_0 e^{-jkR} \left[ \frac{1}{(kR)^2} - \frac{j}{(kR)^3} \right] \cos \theta \quad (9.8b)$$

$$\widetilde{E}_{\theta} = \frac{I_0 l k^2}{4\pi} \eta_0 e^{-jkR} \left[ \frac{j}{kR} + \frac{1}{(kR)^2} - \frac{j}{(kR)^3} \right] \sin \theta,$$

$$(9.8c)$$

For Short Dipole:

where  $\eta_0 = \sqrt{\mu_0/\varepsilon_0} \cong 120\pi$  ( $\Omega$ ) is the intrinsic impedance of free space. The remaining components  $(\widetilde{H}_R, \widetilde{H}_{\theta}, \text{ and } \widetilde{E}_{\phi})$  are everywhere zero.

And  $k = \omega/c = 2\pi/\lambda$ 

9-1.1 Far-Field Approximation

For Far Field Approximation:  $R \gg \lambda$  or, equivalently,  $kR = 2\pi R/\lambda \gg 1$ 

This condition allows us to neglect the terms varying as  $1/(kR)^2$  and  $1/(kR)^3$  in Eqs. (9.8a) to (9.8c) in favor of the terms varying as 1/kR, which yields the far-field expressions

$$\widetilde{E}_{\theta} = \frac{j I_0 l k \eta_0}{4\pi} \left(\frac{e^{-jkR}}{R}\right) \sin \theta \quad (V/m), \quad (9.9a)$$
$$\widetilde{H}_{\phi} = \frac{\widetilde{E}_{\theta}}{\eta_0} \qquad (A/m), \quad (9.9b)$$

And  $\widetilde{E}_R$  is negligible. Power Density . 9-1.2 Given  $\tilde{\mathbf{E}}$  and  $\tilde{\mathbf{H}}$  in phasor form, the time-average Poynting vector of the radiated wave, which is also called the power density.  $\mathbf{S}_{av} = \frac{1}{2} \mathfrak{Re} \left( \widetilde{\mathbf{E}} \times \widetilde{\mathbf{H}}^* \right) \qquad (W/m^2).$  $S(R,\theta) = \left(\frac{\eta_0 k^2 I_0^2 l^2}{32\pi^2 R^2}\right) \sin^2 \theta$ For the short dipole, use of Eqs. (9.9a) and (9.9b) gives  $\mathbf{S}_{av} = \hat{\mathbf{R}} S(R, \theta),$ (9.11)  $= S_0 \sin^2 \theta$  (W/m<sup>2</sup>). (9.12) With the normalized radiation intensity  $F(\theta, \phi)$ ,  $F(\theta, \phi) = \frac{S(R, \theta, \phi)}{S_{max}}$  (dimensionless). For Hertzian dipole :  $S_{\max} = S_0 = \frac{\eta_0 k^2 I_0^2 l^2}{32\pi^2 R^2}$ 9-2 Antenna Radiation Characteristics . And in the spherical coordinate system :  $dA = R^2 \sin \theta \, d\theta \, d\phi$ ,  $dP_{\rm rad} = \mathbf{S}_{\rm av} \cdot d\mathbf{A} = \mathbf{S}_{\rm av} \cdot \hat{\mathbf{R}} dA = S dA$ and the solid angle  $d\Omega$  associated with dA, defined as the subtended area divided by  $R^2$ , is given by  $d\Omega = \frac{dA}{R^2} = \sin\theta \, d\theta \, d\phi \quad (\text{sr}). \quad (9.18)$   $dP_{\text{rad}} = R^2 \, S(R, \theta, \phi) \, d\Omega.$  $P_{\rm rad} = R^2 \int_{\phi=0}^{2\pi} \int_{\theta=0}^{\pi} S(R,\theta,\phi) \sin\theta \, d\theta \, d\phi$  $= R^2 S_{\max} \int_{\phi=0}^{2\pi} \int_{\theta=0}^{\pi} F(\theta, \phi) \sin \theta \, d\theta \, d\phi$  $= R^2 S_{\text{max}} \iint F(\theta, \phi) \, d\Omega \qquad (W), \quad (9.20)$ (Total Radiated Power)

## 9-2.5 Radiation Resistance

$$P_{rad} = \frac{1}{2} I_0^2 R_{rad},$$

$$P_{loss} = \frac{1}{2} I_0^2 R_{loss},$$
where  $l_h$  is the amplitude of the sinusoidal current excitting the antenna.
$$s = \frac{P_{rad}}{P_h} = \frac{P_{rad}}{P_{rad} + P_{loss}} = \frac{R_{rad}}{R_{rad} + R_{loss}}.$$

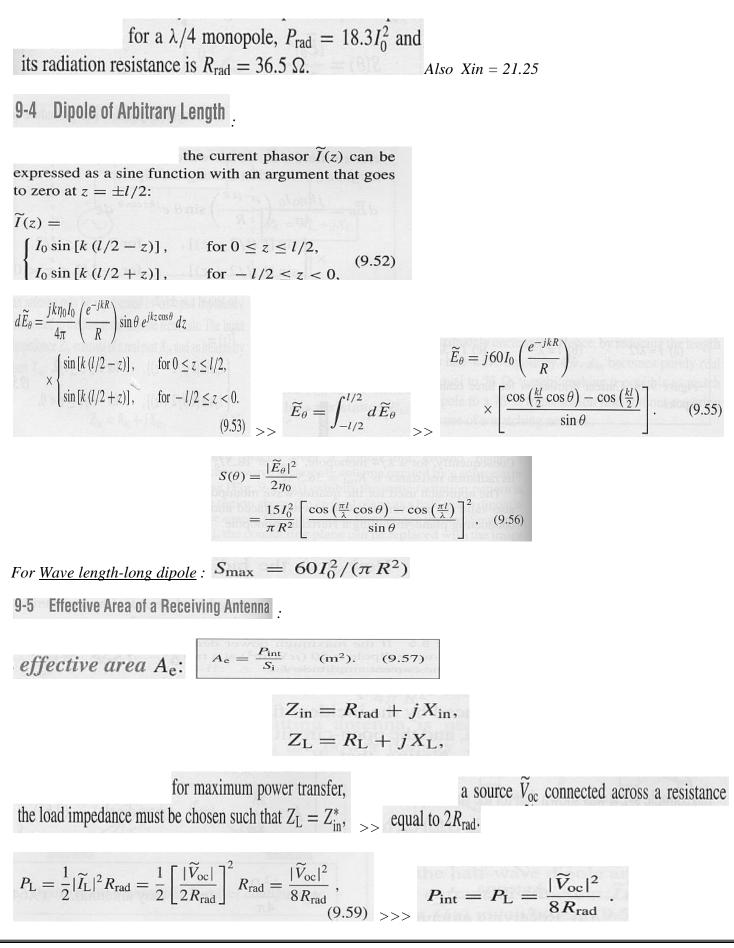
$$(9.31)$$
Resistance or Circler wire of length 1 and radius a
$$R_{losse} = \frac{1}{2\pi ca} \sqrt{\frac{\pi f f \mu_c}{\sigma_c}},$$
For Hertzian dipole:
$$P_{rad} = \frac{4\pi R^2}{1.5} \times \frac{15\pi T_0^2}{R^2} \left(\frac{f}{\lambda}\right)^2,$$

$$R_{rad} = 80\pi^2 (f/\lambda)^2 \quad (see derivation in Example 9.3)$$
9.3 Half-Wave Dipole Antenna
$$f(t) = I_0 \cos \omega t \cos kz = \Re \left[I_0 \cos kz e^{itm}\right], \quad \tilde{t}(z) = I_0 \cos kz, \quad \frac{-\lambda}{4} \le z \le \frac{\lambda}{4}.$$

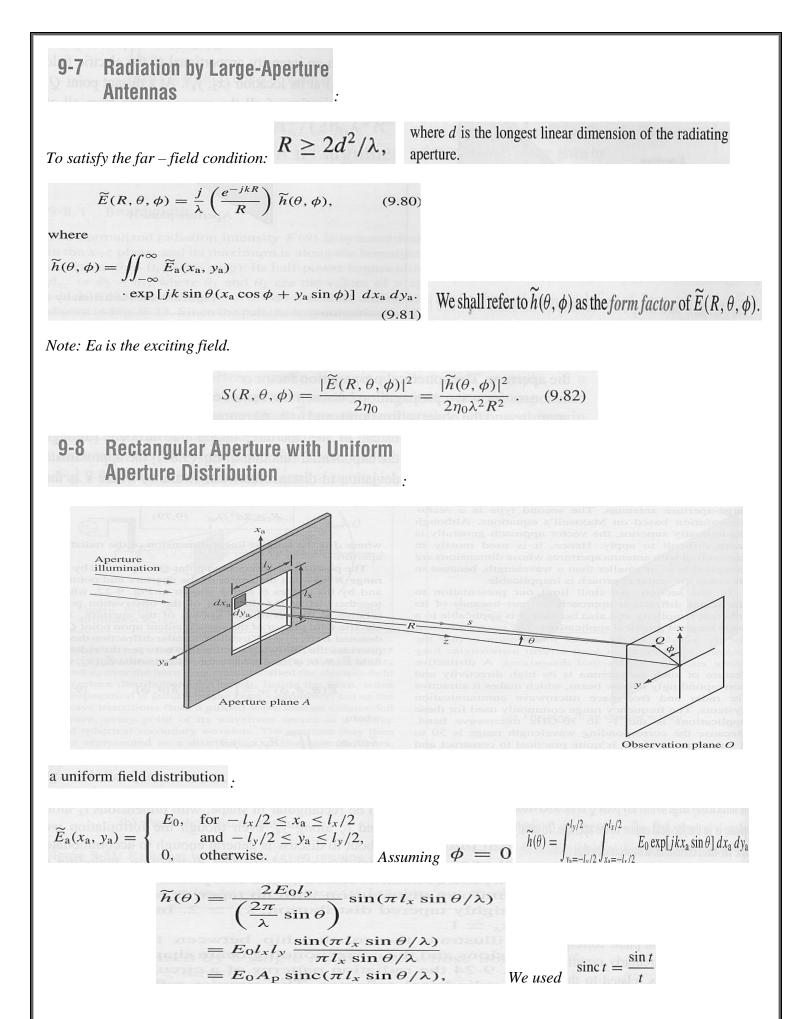
$$f(z) = H_a \log kz, \quad \frac{-\lambda}{4} \le z \le \frac{\lambda}{4}.$$

$$f(z) = \frac{1}{4\pi} \tilde{t}(z) dz \left(\frac{e^{-kz}}{s}\right) \sin \theta_s.$$
Two Approximations:
$$I \cdot \frac{1/s \simeq 1/R}{Also} \theta_s \simeq \theta. \quad (Magnitude Approximation)$$
2.  $s \simeq R - z \cos \theta. \quad (Phase Approximation)$ 





$$S_{i} = \frac{|\tilde{E}_{i}|^{2}}{2\eta_{0}} = \frac{|\tilde{E}_{i}|^{2}}{240\pi} \cdot \sum_{s \to s \to s} A_{e} = \frac{P_{int}}{S_{i}} = \frac{30\pi |\tilde{V}_{oe}|^{2}}{R_{rad}|\tilde{E}_{i}|^{2}} \cdot \frac{A_{e} = \frac{3A_{e}}{S_{i}}}{R_{rad}|\tilde{E}_{i}|^{2}} \cdot \frac{A_{e} = \frac{3A_{e}}{S_{i}}}{R_{rad}|\tilde{E}_{i}|^{2}} \cdot \frac{A_{e} = \frac{3A_{e}}{S_{i}}}{R_{rad}|\tilde{E}_{i}|^{2}} \cdot \frac{A_{e} = \frac{3A_{e}}{S_{i}}}{R_{rad}|\tilde{E}_{i}|^{2}} \cdot \frac{A_{e}}{S_{i}} = \frac{S_{e}}{S_{i}} \cdot \frac{A_{e}}{S_{i}} = \frac{S_{e}}{S_{i}} \cdot \frac{A_{e}}{S_{i}} - \frac{S_{e}}{S_{i}} \cdot \frac{S_{e}}{S_{i}} - \frac{S_{e}}{S_{i}} \cdot \frac{A_{e}}{S_{i}} - \frac{S_{e}}{S_{i}} \cdot \frac{S_{e}}{S_{i}} - \frac{S_{e}}{S_{i}} - \frac{S_{e}}{S_{i}} \cdot \frac{S_{e}}{S_{i}} - \frac{S_{e}}{S_{i}} - \frac{S_{e}}{S_{i}} - \frac{S_{e}}{S_{i}} - \frac{S_{e}}{S_{i}} - \frac{S_{e}}{S_{i}} - \frac{S_{e$$



And from equation 9.82 >>  $S(R,\theta) = S_0 \operatorname{sinc}^2(\pi l_x \sin \theta/\lambda)$  (x-z plane), (9.89) where  $S_0 = E_0^2 A_p^2/(2\eta_0 \lambda^2 R^2)$  $F(\theta) = \frac{S(R,\theta)}{S_{\max}}$ = sinc<sup>2</sup> $(\pi l_x \sin \theta / \lambda)$  $= \operatorname{sinc}^2(\pi \gamma)$  (x-z plane),  $>>> \gamma = (l_x/\lambda) \sin \theta$ 9-8.1 Beamwidth  $\beta_{xz} = \theta_2 - \theta_1 And \theta_1 = -\theta_2 >>> \beta_{xz} = 2\theta_2$  $F(\theta_2) = \operatorname{sinc}^2(\pi l_x \sin \theta / \lambda) = 0.5 >> (from \ tables) >> \frac{\pi l_x}{\lambda} \sin \theta_2 = 1.39 >> \sin \theta_2 = 0.44 \frac{\lambda}{l_x}$ A similar solution for the y-z plane ( $\phi = \pi/2$ ) gives Because  $\lambda/l_x \ll 1_{\dots} \sin \theta_2 \simeq \theta_2$ ,  $\beta_{xz} = 2\theta_2 \simeq 2 \sin \theta_2 = 0.88 \frac{\lambda}{l_x}$   $\beta_{yz} = 0.88 \frac{\lambda}{l_y}$  (rad). (9.94b)  $\beta_{xz} = k_x \frac{\lambda}{L} , \quad (9.95)$ where  $k_x$  is a constant related to the steepness of the taper. For a uniform distribution with no taper,  $k_x = 0.88$ , and for a highly tapered distribution,  $k_x \simeq 2$ . In the typical case,  $k_{\rm r} \simeq 1$ . For a circularly symmetric antenna pattern  $\beta \simeq \lambda/d$ .  $\beta_{xz} \simeq \frac{\lambda}{l_x} \quad \beta_{yz} \simeq \frac{\lambda}{l_y}$ For a cylindrical reflector Directivity and Effective Area 9-8.2  $D = \frac{4\pi A_{\rm e}}{\lambda^2}$  $D\simeq rac{4\pi}{eta_{xz}eta_{yz}} \ \ D\simeq rac{4\pi\,l_xl_y}{\lambda^2}=rac{4\pi\,A_{
m p}}{\lambda^2} \ .$ for aperture antennas, their effective apertures are approximately equal to their physical apertures; that is,  $A_{\rm e} \simeq A_{\rm p}$ .

9-10 A-Element Array with Uniform  
Phase Distribution  
For 
$$\psi_{i} = \psi_{0}$$
  

$$\begin{bmatrix}F_{a}(\theta) = \left|e^{i\theta_{0}}\sum_{l=0}^{N-1}a_{l}e^{ilkd\cos\theta}\right|^{2} \\ = \left|\sum_{l=0}^{N-1}a_{l}e^{ilkd\cos\theta}\right|^{2}.$$
The phase difference between the fields radiated by  
adjacent elements is  
 $\gamma = kd\cos\theta = \frac{2\pi d}{\lambda}\cos\theta.$  (9.112)  
For a uniform amplitude distribution with  $a_{l} = 1$   
For a uniform amplitude distribution with  $a_{l} = 1$   
For a uniform amplitude distribution with  $a_{l} = 1$   
For a uniform amplitude distribution with  $a_{l} = 1$   
For a uniform amplitude distribution with  $a_{l} = 1$   
For a uniform amplitude distribution with  $a_{l} = 1$   
For a uniform amplitude distribution with  $a_{l} = 1$   
For a uniform amplitude distribution with  $a_{l} = 1$   
For a uniform amplitude distribution with  $a_{l} = 1$   
For a uniform amplitude distribution with  $a_{l} = 1$   
For a uniform amplitude distribution with  $a_{l} = 1$   
For a uniform amplitude distribution with  $a_{l} = 1$   
For Electronic Scenning of Arrays :  
For Electronic steering  $\psi_{l} = -i\delta$   
For Electronic steering  $\psi_{l} = -i\delta$   
For  $Electronic steering$   $\psi_{l} = -i$ 

where

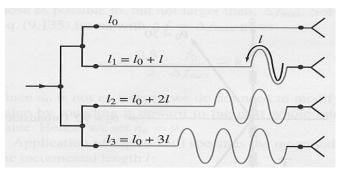
>>

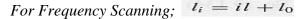
$$\gamma' = kd\cos\theta - \delta.$$
 And  $\delta = kd\cos\theta_0.$  (9.125)  $\gamma' = kd(\cos\theta - \cos\theta_0).$  (9.126)

## 9-11.1 Uniform-Amplitude Excitation

$$F_{\rm an}(\gamma') = \frac{\sin^2(N\gamma'/2)}{N^2 \sin^2(\gamma'/2)}$$

#### 9-11.2 Array Feeding





where  $l_0$  is the path length of the zeroth element. Wave propagation at a frequency f on a transmission line of length  $l_i$  is characterized by a phase factor  $e^{-j\beta l_i}$ , where  $\beta = 2\pi f/u_p$  is the phase constant of the line and  $u_p$ is its propagation velocity >>  $\psi_{i}(f) = -\beta(l_{i} - l_{0}) = -\frac{2\pi}{u_{p}}f(l_{i} - l_{0})$  $= -\frac{2\pi i}{u_{p}}fl. \quad (9.129)$  *let*  $l = \frac{n_{0}u_{p}}{f_{0}}$ 

$$\psi_{1}(f_{0} + \Delta f) = -\frac{2\pi}{u_{p}}(f_{0} + \Delta f)l$$

$$= -\frac{2\pi f_{0}l}{u_{p}} - \left(\frac{2\pi l}{u_{p}}\right) \Delta f$$

$$= -2n_{0}\pi - 2n_{0}\pi \left(\frac{\Delta f}{f_{0}}\right)$$

$$= -2n_{0}\pi - \delta, \qquad \text{with} \qquad \delta = 2n_{0}\pi \left(\frac{\Delta f}{f_{0}}\right).$$

Similarly,  $\psi_2(f_0 + \Delta f) = 2\psi_1$  and  $\psi_3(f_0 + \Delta f) = 3\psi_1$ . ... Ignore  $2\pi$  and its multiples (no influence of relative phases).

$$\cos \theta_0 = \frac{2n_0 \pi}{kd} \left(\frac{\Delta f}{f_0}\right).$$
 (Using equation 125)

Additional Formulas You Might Need:

$$\Gamma = \frac{R_{\rm rad} - Z_0}{R_{\rm rad} + Z_0} \text{ standing wave ratio: } S = \frac{1 + |\Gamma|}{1 - |\Gamma|} \text{ (See problem 12)}$$

Voltage Reflection coefficient:

For Direct and Reflected Waves from antenna:

$$S = \frac{|E|^2}{2\eta_0} E_{\mathbf{d}} = \sqrt{2\eta_0 S_{\mathbf{i}}} e^{-jkR} E_{\mathbf{r}} = \left(\sqrt{\frac{30\eta_0}{\pi}} \frac{I_0}{R'} e^{-jkR'}\right) \Gamma.$$

| i flos<br>io wi  | Any Medium   | Lossless<br>Medium<br>$(\sigma = 0)$ | Low-loss<br>Medium<br>$(\varepsilon''/\varepsilon' \ll 1)$ | GoodConductor $(\varepsilon''/\varepsilon' \gg 1)$ | Units   |
|------------------|--|--------------------------------------|--|--|---------|
| α =              | $\omega \left[ \frac{\mu \varepsilon'}{2} \left[ \sqrt{1 + \left( \frac{\varepsilon''}{\varepsilon'} \right)^2} - 1 \right] \right]^{1/2}$ | 0                                    | $\frac{\sigma}{2}\sqrt{\frac{\mu}{\varepsilon}}$           | $\sqrt{\pi f \mu \sigma}$                          | (Np/m)  |
| $\beta =$        | $\omega \left[ \frac{\mu \varepsilon'}{2} \left[ \sqrt{1 + \left( \frac{\varepsilon''}{\varepsilon'} \right)^2 + 1} \right] \right]^{1/2}$ | $\omega\sqrt{\mu \varepsilon}$       | $\omega\sqrt{\muarepsilon}$                                | $\sqrt{\pi f \mu \sigma}$                          | (rad/m) |
| $\eta_{\rm c} =$ | $\sqrt{rac{\mu}{arepsilon'}} \left(1-jrac{arepsilon''}{arepsilon'} ight)^{-1/2}$   | $\sqrt{\frac{\mu}{\varepsilon}}$     | $\sqrt{\frac{\mu}{\varepsilon}}$ (m)                       | $(1+j)\frac{\alpha}{\sigma}$                       | (Ω)     |
| <sub>p</sub> =   | $\omega/\beta$   | $1/\sqrt{\mu\varepsilon}$            | $1/\sqrt{\mu\varepsilon}$                                  | $\sqrt{4\pi f/\mu\sigma}$                          | (m/s)   |
| $\lambda =$      | $2\pi/\beta = u_{\rm p}/f$   | $u_{\rm p}/f$                        | $u_{\rm p}/f$  | $u_{\rm p}/f$                                      | (m)     |

$$\begin{array}{c} \theta_{i} = \theta_{r} \quad \text{(Snell's law of reflection)}, \quad (8.28a) \\ \frac{\sin \theta_{i}}{\sin \theta_{i}} = \frac{u_{p_{2}}}{u_{p_{1}}} = \sqrt{\frac{\mu_{1}\varepsilon_{1}}{\mu_{2}\varepsilon_{2}}} \\ \text{(Snell's law of refraction)}. \quad (8.28b) \end{array}$$

$$\frac{\sin \theta_{t}}{\sin \theta_{i}} = \frac{n_{1}}{n_{2}} = \sqrt{\frac{\mu_{r_{1}}\varepsilon_{r_{1}}}{\mu_{r_{2}}\varepsilon_{r_{2}}}} \cdot \frac{\sin \theta_{t}}{\sin \theta_{i}} = \frac{n_{1}}{n_{2}} = \sqrt{\frac{\varepsilon_{r_{1}}}{\varepsilon_{r_{2}}}} = \frac{\eta_{2}}{\eta_{1}} \quad (\text{for } \mu_{1} = \mu_{2}), \quad (8.31)$$
*Where* where  $\eta = \sqrt{\mu/\varepsilon}$  is the intrinsic impedance

Table 8-2: Expressions for  $\Gamma$ ,  $\tau$ , R, and T for wave incidence from a medium with intrinsic impedance  $\eta_1$  onto a medium with intrinsic impedance  $\eta_2$ . Angles  $\theta_i$  and  $\theta_t$  are the angles of incidence and transmission, respectively.

| Normal Incidence<br>$\theta_i = \theta_t = 0$      | Perpendicular<br>Polarization  | Parallel<br>Polarization   |
|--|--|--|
| $\Gamma = \frac{\eta_2 - \eta_1}{\eta_2 + \eta_1}$ | $\Gamma_{\perp} = \frac{\eta_2 \cos \theta_i - \eta_1 \cos \theta_t}{\eta_2 \cos \theta_i + \eta_1 \cos \theta_t}$   | $\Gamma_{\parallel} = \frac{\eta_2 \cos \theta_t - \eta_1 \cos \theta_i}{\eta_2 \cos \theta_t + \eta_1 \cos \theta_i}$   |
| $\tau = \frac{2\eta_2}{\eta_2 + \eta_1}$           | $\tau_{\perp} = \frac{2\eta_2 \cos \theta_i}{\eta_2 \cos \theta_i + \eta_1 \cos \theta_t}$   | $\tau_{\parallel} = \frac{2\eta_2 \cos \theta_i}{\eta_2 \cos \theta_t + \eta_1 \cos \theta_i}$   |
| $\tau = 1 + \Gamma$                                | $	au_{\perp} = 1 + \Gamma_{\perp}$   | $\tau_{\parallel} = (1 + \Gamma_{\parallel}) \frac{\cos \theta_{\rm i}}{\cos \theta_{\rm t}}$  |
| $R =  \Gamma ^2$                                   | $R_{\perp} =  \Gamma_{\perp} ^2$   | $R_{\parallel} =  \Gamma_{\parallel} ^2$   |
| $T =  \tau ^2 \left(\frac{\eta_1}{\eta_2}\right)$  | $T_{\perp} =  \tau_{\perp} ^2 \frac{\eta_1 \cos \theta_{\rm t}}{\eta_2 \cos \theta_{\rm i}}$   | $T_{\parallel} =  \tau_{\parallel} ^2 \frac{\eta_1 \cos \theta_t}{\eta_2 \cos \theta_i}$   |
| T = 1 - R  | $T_{\perp} = 1 - R_{\perp}$  | $T_{\parallel} = 1 - R_{\parallel}$  |
|  | $\theta_{1} = \theta_{t} = 0$ $\Gamma = \frac{\eta_{2} - \eta_{1}}{\eta_{2} + \eta_{1}}$ $\tau = \frac{2\eta_{2}}{\eta_{2} + \eta_{1}}$ $\tau = 1 + \Gamma$ $R =  \Gamma ^{2}$ $T =  \tau ^{2} \left(\frac{\eta_{1}}{\eta_{2}}\right)$ | $\begin{array}{ll} \theta_{i} = \theta_{t} = 0 & \\ \hline Polarization \\ \hline \Gamma = \frac{\eta_{2} - \eta_{1}}{\eta_{2} + \eta_{1}} & \\ \Gamma_{\perp} = \frac{\eta_{2} \cos \theta_{i} - \eta_{1} \cos \theta_{t}}{\eta_{2} \cos \theta_{i} + \eta_{1} \cos \theta_{t}} \\ \hline \tau = \frac{2\eta_{2}}{\eta_{2} + \eta_{1}} & \\ \tau_{\perp} = \frac{2\eta_{2} \cos \theta_{i}}{\eta_{2} \cos \theta_{i} + \eta_{1} \cos \theta_{t}} \\ \hline \tau = 1 + \Gamma & \\ \tau_{\perp} = 1 + \Gamma_{\perp} \\ \hline R =  \Gamma ^{2} & \\ R_{\perp} =  \Gamma_{\perp} ^{2} \\ \hline T =  \tau ^{2} \left(\frac{\eta_{1}}{\eta_{2}}\right) & \\ T_{\perp} =  \tau_{\perp} ^{2} \frac{\eta_{1} \cos \theta_{t}}{\eta_{2} \cos \theta_{i}} \end{array}$ |

(See problem 38)

#### Tables:

| Material  | <b>Conductivity</b> , $\sigma$ (S/m)   | Material  | <b>Conductivity</b> , $\sigma$ (S/m)   |   | unio and no -  | $4\pi \times 10^{-7}$ H/m.   |  |
|---|--|---|--|---|--|--|--|
| onductors   | (1850)   | Semiconductors  |  | $\mu - p$   | $c_{\Gamma}\mu_0$ and $\mu_0 =$  | Relative   | (iovisi see 16voi)   |
| Silver  | $6.2 \times 10^{7}$  | Pure germanium  | 2.2  | 1   | 220  |  | molony   |
| Copper  | $5.8 \times 10^7$  | Pure silicon  | $4.4 \times 10^{-4}$   |   | terial   | <b>Permeability</b> , $\mu_r$  | colts  |
| Gold  | $4.1 \times 10^7$  | Insulators  |  | Diamagneti  | C  |  | lio mustores   |
| Aluminum  | $000.2 - 000 + 3.5 \times 10^7$  | Wet soil  | $\sim 10^{-2}$   | Bismuth   |  | $0.99983 \simeq 1$   | 14   |
| Tungsten  | $1.8 \times 10^{7}$  | Fresh water   | $\sim 10^{-3}$   | Gold  |  | $0.99996 \simeq 1$   | (and (dry)   |
| Zinc  | $1.7 \times 10^{7}$  | Distilled water   | $\sim 10^{-4}$   | Mercury   |  | $0.99997 \simeq 1$   | raffin   |
|   | $1.5 \times 10^7$  | Dry soil  | $\sim 10^{-4}$   | Silver  |  | $0.99998 \simeq 1$   | olycthylene av   |
|   | 107 100 100 107  | Glass   | $10^{-12}$   | The second se   |  |  | iystyrene dia  |
| Bronze  | 107  | Hard rubber   | $10^{-15}$   | Copper  |  | $0.99999 \simeq 1$   | 300  |
| Tin   | $9 \times 10^{6}$  | Paraffin  | $10^{-15}$   | Water   | - nonline  | $0.99999 \simeq 1$   | ibber 1  |
| Lead  | $5 \times 10^{6}$  | Mica  | $10^{-15}$   | Paramagnet  | ic   |  | -wol me sawl   |
| Mercury   | 10 <sup>6</sup>  | Fused quartz  | $10^{-17}$   | Air   |  | $1.000004 \simeq 1$  | China are deale  |
| Carbon  | $3 \times 10^4$  | Wax   | $10^{-17}$   | Aluminur  | n  | $1.00002 \simeq 1$   | 1. ROIL 101 . 310  |
| Seawater  | 5 × 10<br>4  | Wax   | 10   | Tungsten  |  | $1.00002 \simeq 1$   |  |
| Animal body (avera  | T  |   |  | Titanium  |  |  | haldal   |
|   |  | (20% C)   |  |   |  | $1.0002 \simeq 1$  |  |
| icse are low-freque   | ency values at room temperatu  | ic (20°C).  |  | Platinum  |  | $1.0003 \simeq 1$  | 16 15  |
| PHEF  | DRICAL C<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial t} \\ A \end{vmatrix}$<br>RICAL C   | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\partial}{\partial \phi} \frac{\partial}{\partial z} = 0$   | <b>NATES</b> ( $\hat{\mathbf{r}} = \frac{\partial A_z}{\partial \phi} - \frac{\partial A_{\phi}}{\partial z}$ )<br><b>NATES</b>  | $+ \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$   |  |  |  |
| SPHER   | $\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{r}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \\ \mathbf{R} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \end{vmatrix}$   | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial \phi} = \frac{\partial}{\partial z} = \frac{\partial}{\partial \phi} \frac{\partial}{\partial z}$   | <b>NATES</b> (<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_{\phi}}{\partial z} \right)$<br><b>NATES</b><br>$\begin{bmatrix} \mathbf{i} & \theta \\ \overline{\phi} \\ \theta & \partial A_{\phi} \end{bmatrix}$  | $(r, \phi, z)$<br>$+\hat{\phi}\left(\frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r}\right)$   | $+\hat{\mathbf{z}}\frac{1}{r}\left[\frac{\partial}{\partial r}\right]$   | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$   | $\left[\frac{R}{2}\right]$   |
| SPHEF<br>⊽×4  | DRICAL<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial r} \\ \frac{\partial}{\partial r} \\ \mathbf{RICAL} & \mathbf{C} \\ \mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \theta} \end{vmatrix}$  | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial \phi} = \frac{\partial}{\partial z} = \frac{\partial}{\partial \phi} \frac{\partial}{\partial z}$   | NATES (<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_{\phi}}{\partial z} \right)$<br>NATES<br>$\begin{bmatrix} \mathbf{i} & \theta \\ \phi \\ \theta & A_{\phi} \end{bmatrix}$<br>$+ \hat{\mathbf{\theta}} \frac{1}{R} \left[ \frac{1}{\sin \theta} \right]$  | $(r, \phi, z)$<br>$+\hat{\phi}\left(\frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r}\right)$<br>$(R, \theta, \phi)$  | $+\hat{\mathbf{z}}\frac{1}{r}\left[\frac{\partial}{\partial r}(\mathbf{z})\right]$   | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$   |  |
| PHEF<br>$\nabla \times A$<br><u>Pransforma</u><br>Cartesian t   | DRICAL<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{r}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \end{vmatrix}$ RICAL C<br>$\mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ = \hat{\mathbf{R}} \frac{1}{R \sin \theta} \begin{bmatrix} \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \theta} \end{vmatrix}$ ation Coordinates the second sec   | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\hat{\phi}r}{rA_{\phi}} \frac{\hat{z}}{A_{z}} = \frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\hat{\phi}r}{rA_{\phi}} \frac{\hat{z}}{A_{z}} = \frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial \phi} = \frac{\hat{z}}{\partial \phi} \frac{\hat{z}}{\partial \phi} \frac{\hat{z}}{\partial \phi} = \frac{\hat{z}}{\partial \phi} \frac{\hat{z}}{\partial \phi} \frac{\hat{z}}{\partial \phi} = \frac{\hat{z}}{\partial \phi} $  | NATES (<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_{\phi}}{\partial z} \right)$<br>NATES<br>$\hat{\mathbf{n}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_{\phi}}{\partial z} \right)$<br>NATES<br>$\hat{\mathbf{n}} \left( \frac{1}{\phi} \right)$<br>$\hat{\mathbf{n}} \left( \frac{1}{\phi} \right)$<br>$\hat{\mathbf{n}} = \hat{\mathbf{n}} \cos \phi$   | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $= \frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $= \frac{\partial A_R}{\partial \phi} + \hat{\mathbf{y}} \sin \phi$   | $+\hat{\mathbf{z}}\frac{1}{r}\left[\frac{\partial}{\partial r}\right]$ $+\hat{\mathbf{\varphi}}\frac{1}{R}\left[\frac{\partial}{\partial r}\right]$ $\mathbf{A}_{r}=\mathbf{A}$  | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R}(RA_{\theta}) - \frac{\partial A}{\partial \theta}$ Vector Component A <sub>x</sub> cos $\phi + A_y$ si   | tin $\phi$   |
| PHEF<br>$ abla \times A$<br>Transforma  | DRICAL<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial r} \\ \frac{\partial}{\partial R} \end{vmatrix}$ RICAL C<br>$\mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ A_R \\ - \hat{\mathbf{R}} \frac{1}{R \sin \theta} \begin{bmatrix} \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \theta} \end{vmatrix}$ ation Coordin<br>$\mathbf{x} = \frac{1}{\sqrt{X^2}} \begin{vmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial \theta} $   | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\hat{\phi}r}{rA_{\phi}} \frac{\hat{z}}{A_{z}} = \frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\hat{\phi}r}{rA_{\phi}} \frac{\hat{z}}{A_{z}} = \frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial \phi} = \frac{\hat{z}}{\partial \phi} \frac{\hat{z}}{\partial \phi} \frac{\hat{z}}{\partial \phi} = \frac{\hat{z}}{\partial \phi} \frac{\hat{z}}{\partial \phi} \frac{\hat{z}}{\partial \phi} = \frac{\hat{z}}{\partial \phi} $  | NATES (<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_{\phi}}{\partial z} \right)$<br>NATES<br>$\begin{bmatrix} \mathbf{i} & \theta \\ \phi \\ \phi \\ \phi \end{bmatrix} + \hat{\mathbf{\theta}} \frac{1}{R} \left[ \frac{1}{\sin \theta} \right]$  | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $= \frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $= \frac{\partial A_R}{\partial \phi} + \hat{\mathbf{y}} \sin \phi$   | $+\hat{\mathbf{z}}\frac{1}{r}\left[\frac{\partial}{\partial r}\right]$ $+\hat{\mathbf{\varphi}}\frac{1}{R}\left[\frac{\partial}{\partial r}\right]$ $\mathbf{A}_{r}=\mathbf{A}_{\phi}$   | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ <u>Vector Components</u> $A_x \cos \phi + A_y \sin \phi$   | tin $\phi$   |
| Cartesian t<br>cylindric  | DRICAL<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial r} \\ \frac{\partial}{\partial r} \\ \mathbf{RICAL} & \mathbf{C} \\ \mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ - \hat{\mathbf{R}} \\ \frac{1}{R \sin \theta} \begin{bmatrix} \hat{\mathbf{d}} \\ \frac{\partial}{\partial \theta} $                       | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\hat{\phi}r}{rA_{\phi}} \frac{\hat{z}}{A_{z}} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial z} = \frac{\hat{\theta}r}{rA_{\phi}} \frac{\hat{\theta}r}{A_{z}} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi$  | NATES (<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_{\phi}}{\partial z} \right)$<br>NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_{\phi}}{\partial z} \right)$<br>NATES<br>$\hat{\mathbf{p}} \\ \frac{\partial A_{\phi}}{\partial \phi} + \hat{\mathbf{\theta}} \frac{1}{R} \left[ \frac{1}{\sin \phi} \right]$<br>$\hat{\mathbf{r}} = \hat{\mathbf{x}} \cos \phi$<br>$\hat{\boldsymbol{\phi}} = -\hat{\mathbf{x}} \sin \phi$  | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} + \hat{\mathbf{y}} \cos \phi$   | $+ \hat{\mathbf{z}} \frac{1}{r} \left[ \frac{\partial}{\partial r} (\mathbf{z}) \right] + \hat{\mathbf{\varphi}} \frac{1}{R} \left[ \frac{\partial}{\partial r} (z$  | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ <u>Vector Components</u> $A_x \cos \phi + A_y \sin \phi$   | $\frac{1}{1}$ in $\phi$<br>$\cos \phi$   |
| Cartesian t<br>cylindric  | DRICAL C<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \end{vmatrix}$ RICAL C<br>$\mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ = \hat{\mathbf{R}} \frac{1}{R \sin \theta} \begin{bmatrix} \frac{\partial}{\partial \theta} \\ \partial$    | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\hat{\phi}r}{rA_{\phi}} \frac{\hat{z}}{A_{z}} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial z} = \frac{\hat{\theta}r}{rA_{\phi}} \frac{\hat{\theta}r}{A_{z}} = \frac{\hat{\theta}r}{\partial \phi} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial$   | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \left( \frac{\partial \Phi}{\partial \phi} \right) + \hat{\mathbf{\theta}} \frac{1}{R} \left[ \frac{1}{\sin \phi} \right]$ $\frac{\Phi \Phi}{\Phi} + \hat{\mathbf{\theta}} \frac{1}{R} \left[ \frac{1}{\sin \phi} + \hat{\mathbf{\theta}} \frac{1}{R} \right]$ $\hat{\mathbf{r}} = \hat{\mathbf{x}} \cos \phi$ $\hat{\mathbf{p}} = -\hat{\mathbf{x}} \sin \phi$ $\hat{\mathbf{x}} = \hat{\mathbf{r}} \cos \phi$ $\hat{\mathbf{y}} = \hat{\mathbf{r}} \sin \phi$   | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} + \hat{\mathbf{y}} \cos \phi$ $- \hat{\phi} \sin \phi$  | $+ \hat{z} \frac{1}{r} \left[ \frac{\partial}{\partial r} (A_r) \right] + \hat{\Phi} $   | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ Vector Component A <sub>x</sub> cos $\phi + A_y$ si $-A_x \sin \phi + A_y$ si $-A_x \sin \phi + A_y$ si $A_r \cos \phi - A_\phi$ si $A_r \sin \phi + A_\phi$ co  | $\frac{1}{10000000000000000000000000000000000$   |
| PHEF<br>▽×4<br>Transforma<br>Cartesian t<br>cylindrical<br>Cartesian  | DRICAL C<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{r}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \\ \mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ = \hat{\mathbf{R}} \frac{1}{R \sin \theta} \begin{bmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}$ | $\frac{\hat{\phi}r  \hat{z}}{\partial \phi  \partial z} = \frac{\hat{\phi}r  \hat{z}}{\partial \phi  \hat{z}} = \frac{\hat{\phi}r  \hat{z}}{$  | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \left( \frac{\partial \Phi}{\partial \phi} \right) + \hat{\mathbf{\theta}} \frac{1}{R} \left[ \frac{1}{\sin \phi} \right]$ $\frac{\Phi}{\partial \phi} + \hat{\mathbf{\theta}} \frac{1}{R} \left[ \frac{1}{\sin \phi} + \hat{\mathbf{\theta}} \frac{1}{R} \right]$ $\hat{\mathbf{r}} = \hat{\mathbf{x}} \cos \phi$ $\hat{\mathbf{p}} = -\hat{\mathbf{x}} \sin \phi$ $\hat{\mathbf{z}} = \hat{\mathbf{z}}$   | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} + \hat{y} \cos \phi$ $-\hat{\phi} \sin \phi$ $+ \hat{\phi} \cos \phi$   | $+ \hat{\mathbf{z}} \frac{1}{r} \left[ \frac{\partial}{\partial r} \right]$ $+ \hat{\mathbf{\varphi}} \frac{1}{R} \left[ \frac{\partial}{\partial r} \right]$ $A_r = A_r$ $A_{\varphi} = A_z$ $A_{\chi} = A_z$ $A_{\chi} = A_z$  | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \phi}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \phi}$   | $\frac{1}{10000000000000000000000000000000000$   |
| PHEF<br>▽×4<br>Transforma<br>Cartesian t<br>cylindrical<br>Cartesian<br>Cartesian t   | DRICAL C<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{r}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \end{vmatrix}$<br>RICAL C<br>$\mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \end{vmatrix}$<br>$= \hat{\mathbf{R}} \frac{1}{R \sin \theta} \begin{bmatrix} \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \theta} \end{vmatrix}$<br>ation Coordin<br>$\mathbf{x} = r + \sqrt{x^2}$<br>$\mathbf{x} = r \cos n$<br>z = z<br>z = z<br>z = z<br>$\mathbf{x} = r \cos n$<br>z = z<br>$\mathbf{x} = r \cos n$<br>z = z  | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\hat{\phi}r}{rA_{\phi}} \frac{\hat{z}}{A_{z}} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial z} = \frac{\hat{\theta}r}{rA_{\phi}} \frac{\hat{\theta}r}{A_{z}} = \frac{\hat{\theta}r}{\partial \phi} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial$   | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ $\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \frac{\partial \phi}{\partial \phi} + \hat{\mathbf{n}} \frac{1}{R} \left[ \frac{1}{\sin \phi} - \hat{\mathbf{n}} \frac{\partial A_\phi}{\partial \phi} \right]$ $\frac{\mathbf{n}}{\hat{\mathbf{p}}} + \hat{\mathbf{n}} \frac{1}{R} \left[ \frac{1}{\sin \phi} - \hat{\mathbf{n}} \frac{\partial A_\phi}{\partial \phi} \right]$ $\hat{\mathbf{r}} = \hat{\mathbf{r}} \cos \phi$ $\hat{\mathbf{r}} = \hat{\mathbf{r}} \cos \phi$ $\hat{\mathbf{r}} = \hat{\mathbf{r}} \sin \phi$ $\hat{\mathbf{r}} = \hat{\mathbf{r}} \sin \phi$ $\hat{\mathbf{r}} = \hat{\mathbf{r}} \sin \phi$   | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} + \hat{y} \cos \phi$ $-\hat{\phi} \sin \phi$ $+ \hat{\phi} \cos \phi$   | $+\hat{z}\frac{1}{r}\left[\frac{\partial}{\partial r}\right]$ $+\hat{\varphi}\frac{1}{R}\left[\frac{\partial}{\partial r}\right]$ $A_{r} = A$ $A_{\phi} = A$ $A_{z} = A$ $A_{z} = A$ $A_{z} = A$   | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ Vector Component A <sub>x</sub> cos $\phi + A_y$ si $-A_x \sin \phi + A_y$ si $-A_x \sin \phi + A_y$ si $A_r \cos \phi - A_\phi$ si $A_r \sin \phi + A_\phi$ co  | $\frac{1}{10000000000000000000000000000000000$   |
| PHEF<br>V×4<br>Transforma<br>Cartesian t<br>cylindrical<br>Cartesian  | DRICAL C<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{r}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \end{vmatrix}$<br>RICAL C<br>$\mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ $   | $\frac{\hat{\phi}r  \hat{z}}{\partial \phi  \partial z} = \frac{\hat{\phi}r  \hat{z}}{\partial \phi  \hat{z}} = \frac{\hat{\phi}r  \hat{z}}{$  | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ $\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \frac{\partial \phi}{\partial \phi} + \hat{\theta} \frac{1}{R} \left[ \frac{1}{\sin \theta} \right]$ $\frac{\mathbf{v}}{\phi} + \hat{\theta} \frac{1}{R} \left[ \frac{1}{\sin \theta} - \hat{\mathbf{v}} \frac{1}{2} \hat{\mathbf{v}} \right]$ $\hat{\mathbf{r}} = \hat{\mathbf{x}} \cos \phi$ $\hat{\mathbf{v}} = \hat{\mathbf{r}} \sin \phi$ $\hat{\mathbf{z}} = \hat{\mathbf{z}}$ $\hat{\mathbf{x}} = \hat{\mathbf{r}} \cos \phi$ $\hat{\mathbf{y}} = \hat{\mathbf{r}} \sin \phi$ $\hat{\mathbf{z}} = \hat{\mathbf{z}}$ $\hat{\mathbf{k}} = \hat{\mathbf{x}} \sin \theta$ $+ \hat{\mathbf{y}} \sin \theta$ $\hat{\mathbf{\theta}} = \hat{\mathbf{x}} \cos \theta$   | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} + \hat{y} \cos \phi$ $- \hat{\phi} \sin \phi$ $+ \hat{\phi} \cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \phi$   | $+\hat{z}\frac{1}{r}\left[\frac{\partial}{\partial r}\right]$ $+\hat{\varphi}\frac{1}{R}\left[\frac{\partial}{\partial r}\right]$ $A_{r} = A$ $A_{\phi} = A$ $A_{z} = A$   | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ Vector Component of the second seco  | $\frac{dents}{\cos \phi}$ $\frac{dents}{\cos \phi}$ $+ A_z \cos \theta$  |
| Cartesian t<br>Cartesian t<br>Cartesian t<br>Cartesian  | DRICAL C<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \end{vmatrix}$ RICAL C<br>$\mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \partial$  | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\hat{\phi}r}{rA_{\phi}} \frac{\hat{z}}{A_{z}} = \frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\hat{\phi}r}{rA_{\phi}} \frac{\hat{z}}{A_{z}} = \frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial \phi} \frac{\hat{z}}{\partial \phi} = \frac{\hat{z}}{\partial \phi} \hat{$   | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_{\phi}}{\partial z} \right)$ NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_{\phi}}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \frac{\partial \phi}{\partial A_{\phi}} = \frac{1}{R} \left[ \frac{1}{\sin \theta} - \hat{\mathbf{n}} \frac{1}{R} \right]$ $\hat{\mathbf{r}} = \hat{\mathbf{x}} \cos \phi$ $\hat{\mathbf{p}} = -\hat{\mathbf{x}} \sin \phi$ $\hat{\mathbf{z}} = \hat{\mathbf{z}}$ $\hat{\mathbf{x}} = \hat{\mathbf{r}} \cos \phi$ $\hat{\mathbf{y}} = \hat{\mathbf{r}} \sin \phi$ $\hat{\mathbf{z}} = \hat{\mathbf{z}}$ $\hat{\mathbf{x}} = \hat{\mathbf{r}} \cos \phi$ $\hat{\mathbf{y}} = \hat{\mathbf{r}} \sin \phi$ $\hat{\mathbf{z}} = \hat{\mathbf{z}}$ $\hat{\mathbf{x}} = \hat{\mathbf{r}} \cos \phi$ $\hat{\mathbf{y}} = \hat{\mathbf{r}} \sin \phi$ $\hat{\mathbf{z}} = \hat{\mathbf{z}}$ $\hat{\mathbf{x}} = \hat{\mathbf{r}} \cos \phi$ $\hat{\mathbf{y}} = \hat{\mathbf{r}} \sin \phi$ $\hat{\mathbf{z}} = \hat{\mathbf{z}}$ $\hat{\mathbf{x}} = \hat{\mathbf{r}} \cos \phi$ $\hat{\mathbf{y}} = \hat{\mathbf{r}} \sin \phi$ $\hat{\mathbf{z}} = \hat{\mathbf{z}}$ $\hat{\mathbf{x}} = \hat{\mathbf{r}} \cos \phi$ $\hat{\mathbf{z}} = \hat{\mathbf{z}}$ $\hat{\mathbf{z}} = \hat{\mathbf{z}}$   | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} + \hat{y} \cos \phi$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$   | $+\hat{\mathbf{z}}\frac{1}{r}\left[\frac{\partial}{\partial r}\right]$ $+\hat{\mathbf{\varphi}}\frac{1}{R}\left[\frac{\partial}{\partial r}\right]$ $A_{r} = A$ $A_{\phi} = A$ $A_{z} = A$   | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial A_r}{\partial \theta} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial A_r}{\partial \theta} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial A_r}{\partial \theta} (RA_{\theta}) - \frac{\partial A_r}{\partial \theta}$ $\frac{\partial A_r}{\partial \theta} (RA_{\theta}) - \frac{\partial A_r}{\partial \theta}$  | $\frac{dents}{\cos \phi}$ $\frac{dents}{\cos \phi}$ $+ A_z \cos \theta$ $- A_z \sin \theta$  |
| Cartesian t<br>Cartesian t<br>Cartesian t<br>Cartesian t  | DRICAL<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{r}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \end{vmatrix}$<br>RICAL C<br>$\mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}$  | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\hat{\phi}r}{rA_{\phi}} \frac{\hat{z}}{A_{z}} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial z} = \frac{\hat{\theta}r}{rA_{\phi}} \frac{\hat{\theta}r}{A_{z}} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} = \frac{\hat{\theta}r}{\partial$   | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \frac{\partial \phi}{\partial \phi} + \hat{\theta} \frac{1}{R} \left[ \frac{1}{\sin \theta} \right]$ $\hat{\mathbf{r}} = \hat{\mathbf{x}} \cos \phi$ $\hat{\phi} = -\hat{\mathbf{x}} \sin \theta$ $\hat{z} = \hat{z}$ $\hat{\mathbf{x}} = \hat{\mathbf{r}} \cos \phi$ $\hat{g} = \hat{\mathbf{r}} \sin \phi$ $\hat{z} = \hat{z}$ $\hat{\mathbf{x}} = \hat{\mathbf{r}} \cos \phi$ $\hat{g} = \hat{\mathbf{x}} \sin \theta$ $+ \hat{y} \sin \theta$ $\hat{g} = -\hat{\mathbf{x}} \sin \theta$ $\hat{g} = -\hat{\mathbf{x}} \sin \theta$   | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} + \hat{y} \cos \phi$ $- \hat{\phi} \sin \phi$ $+ \hat{\phi} \cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \theta \sin \phi + \hat{z} \cos \theta$ $\phi + \hat{y} \cos \phi$  | $+\hat{z}\frac{1}{r}\left[\frac{\partial}{\partial r}\right]$ $+\hat{\varphi}\frac{1}{R}\left[\frac{\partial}{\partial r}\right]$ $A_{r} = A$ $A_{\phi} = -$ $A_{z} = A$ $A_{z} = $  | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial A_x \cos \phi + A_y \sin \phi}{A_x \sin \phi + A_y \cos \phi}$ $\frac{A_x \sin \phi + A_\phi \cos \phi}{A_x \sin \phi \sin \phi}$ $\frac{A_x \cos \theta \cos \phi}{A_x \cos \theta \sin \phi}$ $-A_x \sin \phi + A_y$   | $\frac{dents}{\cos \phi}$ $\frac{dents}{\cos \phi}$ $+ A_z \cos \theta$ $- A_z \sin \theta$  |
| Cartesian t<br>Cartesian t<br>Cartesian t<br>Cartesian t<br>Cartesian t   | DRICAL C<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \end{vmatrix}$<br>RICAL C<br>$\mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac$  | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} = \frac{\hat{\phi}r}{rA_{\phi}} \frac{\hat{z}}{A_{z}} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial z} = \frac{\hat{\theta}r}{rA_{\phi}} \frac{\hat{\theta}r}{A_{z}} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} = \frac{\hat{\theta}r}{\partial \phi} \frac{\hat{\theta}r}{\partial \phi} = \frac{\hat{\theta}r}{\partial$   | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ $\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $$ | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} + \hat{y} \cos \phi$ $- \hat{\phi} \sin \phi$ $+ \hat{\phi} \cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \theta \sin \phi + \hat{z} \cos \theta$ $\phi + \hat{y} \cos \phi$  | $+\hat{z}\frac{1}{r}\left[\frac{\partial}{\partial r}\right]$ $+\hat{\varphi}\frac{1}{R}\left[\frac{\partial}{\partial r}\right]$ $A_{r} = A$ $A_{\phi} = A$ $A_{z} = A$   | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial A_x \cos \phi + A_y \sin \phi}{A_x \sin \phi + A_y \cos \phi}$ $\frac{A_x \sin \phi + A_\phi \cos \phi}{A_z \sin \theta \sin \phi}$ $\frac{A_x \cos \theta \cos \phi}{A_x \cos \theta \cos \phi}$  | $\frac{1}{100} \frac{1}{100} \frac{1}$ |
| PHEF<br>▽×4<br>Pransforma<br>Cartesian t<br>cylindrical<br>Cartesian t<br>spherical<br>Spherical t                              | DRICAL C<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \end{vmatrix}$<br>RICAL C<br>$\mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac$  | $\frac{\hat{\phi}r}{\partial \phi} \frac{\hat{z}}{\partial z} \bigg _{rA_{\phi}} \frac{\hat{\partial}}{\partial z} \bigg _{z} = \frac{\hat{\partial}}{\partial \phi} \frac{\hat{\partial}}{\partial z} \bigg _{rA_{\phi}} A_{z} \bigg _{z}$ $\frac{\hat{\theta}R}{\partial \phi} \frac{\hat{\theta}R}{\partial \phi} \frac{\hat{\theta}R}{\partial \phi} \bigg _{z}$ $\frac{\hat{\theta}R}{\partial \phi} \frac{\hat{\theta}R}{\partial \phi} \bigg _{z}$ $\frac{\hat{\theta}R}{\partial \phi} (R \sin \theta) - \frac{\hat{\theta}A}{\partial \phi}$ $\frac{\hat{\theta}R}{\partial \phi} \frac{\hat{\theta}R}{\partial \phi} \bigg _{z}$ $\frac{\hat{\theta}R}{\partial \phi} \frac{\hat{\theta}R}{\partial \phi} \frac{\hat{\theta}R}{\partial \phi}$ $\frac{\hat{\theta}R}{\partial \phi} \frac{\hat{\theta}R}{\partial \phi} \frac{\hat{\theta}R}{\partial \phi}$ $\frac{\hat{\theta}R}{\partial \phi} \frac{\hat{\theta}R}{\partial \phi} \frac{\hat{\theta}R}{\partial \phi}$   | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ $\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $\hat{\mathbf{r}} = \hat{\mathbf{x}} \cos \phi$ $\hat{\mathbf{p}} = \hat{\mathbf{r}} \sin \phi$ $\hat{\mathbf{r}} = \hat{\mathbf{x}} \sin \phi$ $\hat{\mathbf{r}} = \hat{\mathbf{r}} \cos \phi$ $\hat{\mathbf{r}} = \hat{\mathbf{r}} \sin \phi$   | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$   | $+ \hat{z} \frac{1}{r} \left[ \frac{\partial}{\partial r} (A_{r}) + \hat{z} \frac{1}{r} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_{r}) + \hat{\varphi} \frac{1}{r} \frac{\partial}{\partial r} (A_{r}) + \hat{\varphi} \frac{\partial}{\partial r} \frac{\partial}{\partial r} + \hat{\varphi} \frac{\partial}{\partial r} \frac{\partial}{\partial r} + \hat{\varphi} \frac{\partial}{\partial r} \frac{\partial}{\partial r} \frac{\partial}{\partial r} + \hat{\varphi} \frac{\partial}{\partial r} \frac{\partial}{\partial r} \frac{\partial}{\partial r} + \hat{\varphi} \frac{\partial}{\partial r} \frac{\partial}{\partial$ | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial}{\partial \phi}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial}{\partial A}$ | $\frac{dents}{dents}$ $\frac{dents}{d$   |
| PHEF<br>▽×4<br>Pransforma<br>Cartesian t<br>cylindrical<br>Cartesian t<br>spherical<br>Spherical t                              | DRICAL C<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{r}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \\ \mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ = \hat{\mathbf{R}} \frac{1}{R \sin \theta} \begin{bmatrix} \hat{\mathbf{A}} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial t} \\ \frac{\partial}$  | $\frac{\hat{\phi}r  \hat{z}}{\partial \phi} = \frac{\partial}{\partial z} = \frac{\partial}{\partial \phi}  \frac{\partial}{\partial z}}{\partial z} = \frac{\partial}{\partial \phi}  \frac{\partial}{\partial z}}{\partial z} = \frac{\partial}{\partial \phi}  \frac{\partial}{\partial z}}{\partial \phi} = \frac{\partial}{\partial \phi}  \frac{\partial}{\partial z}}{\partial \phi} = \frac{\partial}{\partial \phi}  \frac{\partial}{$ | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ $\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $$ | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ | $+\hat{z}\frac{1}{r}\left[\frac{\partial}{\partial r}\right]$ $+\hat{\varphi}\frac{1}{R}\left[\frac{\partial}{\partial r}\right]$ $A_{r} = A$ $A_{q} = A$ $A_{z} = A$  | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial A_x \cos \phi + A_y \sin \phi}{\partial A_x \sin \phi + A_y \sin \phi}$ $\frac{A_z}{A_r \cos \phi - A_{\phi} \sin \phi}$ $\frac{A_z}{A_r \cos \theta \cos \phi}$ $- A_y \sin \theta \sin \phi - A_y \cos \theta \sin \phi$ $- A_x \sin \phi \cos \phi$ $- A_y \cos \theta \sin \phi$ $- A_x \sin \phi \cos \phi$ $- A_x \sin \phi \cos \phi$ $- A_y \cos \theta \sin \phi$ $- A_x \sin \theta \cos \phi$ $- A_\theta \cos \theta \sin \phi$ $- A_\theta \cos \theta \sin \phi$  | $\frac{dents}{\cos \phi}$ $\frac{dents}{\cos \phi}$ $+ A_z \cos \phi$ $- A_z \sin \phi$ $- A_\phi \sin \phi$ $+ A_\phi \cos \phi$  |
| Cartesian t<br>cylindrical<br>Cartesian t<br>cylindrical<br>Cartesian<br>Cartesian t<br>spherical<br>Spherical t<br>Cartesian   | DRICAL C<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \\ \mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ $   | $\frac{\hat{\phi}r  \hat{z}}{\partial \phi} = \frac{\hat{\partial}r  \hat{z}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \hat$  | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ $\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $$ | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$  | $+\hat{z}\frac{1}{r}\left[\frac{\partial}{\partial r}\right]$ $+\hat{\varphi}\frac{1}{R}\left[\frac{\partial}{\partial r}\right]$ $A_{r} = A$ $A_{q} = A$ $A_{z} = A$  | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$   | $\frac{\sin \phi}{\cos \phi}$ $\frac{\sin \phi}{\cos \phi}$ $+ A_z \cos \phi$ $- A_z \sin \phi$ $- A_\phi \sin \phi$ $+ A_\phi \cos \phi$ $\sin \theta$  |
| Cartesian t<br>Cartesian t<br>Cartesian t<br>Cartesian t<br>Spherical t   | DRICAL C<br>$\nabla \times A = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{r}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \\ A = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{r}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ = \hat{\mathbf{R}} \frac{1}{R \sin \theta} \begin{bmatrix} \hat{\mathbf{d}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{R} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{R} \\ \frac{\partial}$  | $\frac{\hat{\phi}r  \hat{z}}{\partial \phi} = \frac{\hat{\partial}r  \hat{z}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \hat$  | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ $\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $$ | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$  | $+\hat{z}\frac{1}{r}\left[\frac{\partial}{\partial r}\left(A_{r}\right) + \hat{\varphi}\frac{1}{R}\left[A_{r}\right] + \hat{\varphi}\frac{1}$  | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial A_x \cos \phi + A_y \sin \phi}{\partial A_x \sin \phi + A_y \sin \phi}$ $\frac{A_z}{A_r \cos \phi - A_{\phi} \sin \phi}$ $\frac{A_z}{A_r \cos \theta \cos \phi}$ $- A_y \sin \theta \sin \phi - A_y \cos \theta \sin \phi$ $- A_x \sin \phi \cos \phi$ $- A_y \cos \theta \sin \phi$ $- A_x \sin \phi \cos \phi$ $- A_x \sin \phi \cos \phi$ $- A_y \cos \theta \sin \phi$ $- A_x \sin \theta \cos \phi$ $- A_\theta \cos \theta \sin \phi$ $- A_\theta \cos \theta \sin \phi$  | $\frac{1}{100} \frac{1}{100} \frac{1}$ |
| SPHEF   | DRICAL C<br>$\nabla \times A = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{r}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \\ A = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{r}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ = \hat{\mathbf{R}} \frac{1}{R \sin \theta} \begin{bmatrix} \hat{\mathbf{d}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{R} \\ \frac{\partial}{\partial R} \\ $   | $\frac{\hat{\phi}r  \hat{z}}{\partial \phi} = \frac{\hat{\partial}r  \hat{z}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \hat$  | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ $\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $$ | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$  | $+\hat{z}\frac{1}{r}\left[\frac{\partial}{\partial r}\left(A_{r}\right) + \hat{\varphi}\frac{1}{R}\left[A_{r}\right] + \hat{\varphi}\frac{1}$  | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$  | $\frac{1}{100} \frac{1}{100} \frac{1}$ |
| SPHEF<br>V × 4<br>Transforma<br>Cartesian t<br>cylindrical<br>Cartesian t<br>Spherical t<br>Cartesian<br>Cartesian<br>Cartesian | DRICAL C<br>$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial t} \\ \frac{\partial}{\partial t} \\ \mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{\mathbf{R}} \\ \frac{\partial}{\partial R} \\ \frac{\partial}{\partial R} \\ = \hat{\mathbf{R}} \frac{1}{R \sin \theta} \begin{bmatrix} \hat{\mathbf{p}} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial R} \\ \frac{\partial}$   | $\frac{\hat{\phi}r  \hat{z}}{\partial \phi} = \frac{\hat{\partial}r  \hat{z}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \frac{\hat{\partial}}{\partial z} = \frac{\hat{\partial}}{\partial \phi} = \hat$  | NATES<br>$\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ $\hat{\mathbf{r}} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right)$ NATES<br>$\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $\hat{\mathbf{n}} \left( \frac{\partial A_z}{\partial \phi} \right)$ $$ | $(r, \phi, z)$ $) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right)$ $(R, \theta, \phi)$ $(R, \theta, \phi)$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ $\frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (RA_{\phi})$ it Vectors $+ \hat{\mathbf{y}} \sin \phi$ $\phi + \hat{\mathbf{y}} \cos \phi$ $- \hat{\phi} \sin \phi$ $+ \hat{\phi} \cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \phi = \hat{\phi} \sin \phi$ $\phi + \hat{\mathbf{y}} \cos \phi$ $\cos \phi$ $\cos \phi$ $\cos \phi$ $\sin \phi + \hat{\mathbf{y}} \cos \phi$ $- \hat{\theta} \sin \phi + \hat{\mathbf{y}} \cos \phi$ $- \hat{\theta} \sin \phi + \hat{\mathbf{y}} \cos \phi$ $- \hat{\theta} \sin \phi$ $\sin \phi$ $\sin \phi$ $\sin \phi$ $\sin \phi$ $\sin \phi$ $\sin \phi$ $- \hat{\theta} \sin \theta$ $+ \hat{\mathbf{y}} \cos \phi$ $- \hat{\theta} \sin \theta$ $+ \hat{\mathbf{y}} \cos \phi$ $- \hat{\theta} \sin \theta$  | $+ \hat{z} \frac{1}{r} \left[ \frac{\partial}{\partial r} (A_r) + \hat{z} \frac{1}{r} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left[ \frac{\partial}{\partial r} (A_r) + \hat{\varphi} \frac{1}{R} \right] + \hat{\varphi} \frac{1}{R} \left$   | $rA_{\phi}) - \frac{\partial A_r}{\partial \phi} \bigg]$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial A}{\partial \theta}$ $\frac{\partial}{\partial R} (RA_{\theta}) - \frac{\partial}{\partial \theta}$  | $\frac{1}{1000} \frac{1}{1000} \frac{1}{1000} \frac{1}{1000} \frac{1}{1000} \frac{1}{1000} \frac{1}{1000} \frac{1}{10000} \frac{1}{10000000000000000000000000000000000$  |



## Hashemite University Collage of Engineering

#### **Electrical Engineering Department**

## Helical Antennas

Supervisor:

Dr. Omar Saraereh

Written By:

Bahaa Ishaq Radi 833150

Wael Malkawi 833149

Completed November 8, 2011

### **EXECUTIVE SUMMURY:**

Helical antennas have long been popular in applications from VHF to microwaves requiring circular polarization, since they have the unique property of naturally providing circularly polarized radiation.

One area that takes advantage of this property is satellite communications. Where more gain is required than can be provided by a helical antenna alone, a helical antenna can also be used as a feed for a parabolic dish for higher gains. As we shall see, the helical antenna can be an excellent feed for a dish, with the advantage of circular polarization.

One limitation is that the usefulness of the circular polarization is limited since it cannot be easily reversed to the other sense, left-handed to right-handed or vice-versa. [1]

## TABLE OF CONTENTS

| EXECUTIVE SUMMARY                      | ii  |
|--|-----|
| TABLE OF CONTENTS                      | iii |
| LIST OF FIGURES                        |     |
|  |     |
| Overview                               | 1   |
| Geometry and operation                 | 1   |
| Impedance, Gain, and Radiation Pattern | 5   |
|  |     |
| REFRENCES                              | 9   |

## List of Figures

| Figure 1: A sketch of a typical helical antenna | l |
|---|---|
| Figure 2: Geometry of Helical Antenna2          |   |
| Figure 3: Radiation Pattern Helical Antenna     | 5 |

#### Overview:

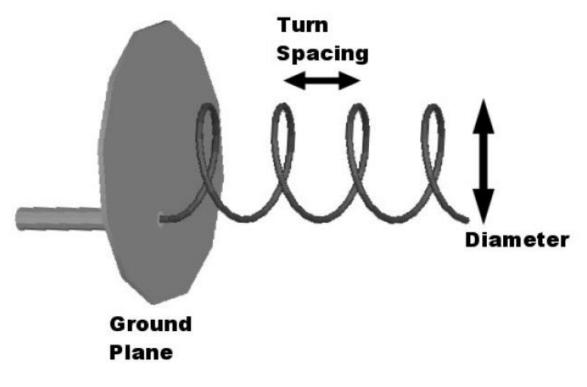
A helical antenna is an antenna consisting of a conducting wire wound in the form of a helix. In most cases, helical antennas are mounted over a ground plane. The feed line is connected between the bottom of the helix and the ground plane. Helical antennas can operate in one of two principal modes: normal mode or axial mode.

In the *normal mode* or *broadside* helix, the dimensions of the helix (the diameter and the pitch) are small compared with the wavelength. The antenna acts similarly to an electrically short dipole or monopole, and the radiation pattern, similar to these antennas is omnidirectional, with maximum radiation at right angles to the helix axis. The radiation is linearly polarized parallel to the helix axis.

In the *axial mode* or *end-fire* helix, the dimensions of the helix are comparable to a wavelength. The antenna functions as a directional antenna radiating a beam off the ends of the helix, along the antenna's axis. It radiates circularly polarized radio waves. [2]

#### Geometry and Operation:

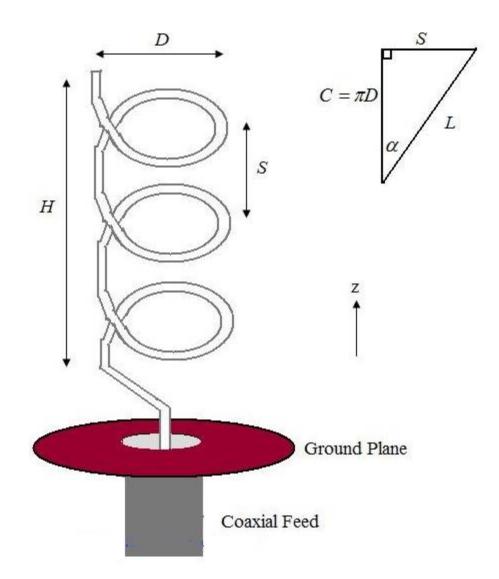
A sketch of a typical helical antenna is shown in Figure 1. The radiating element is a helix of wire, driven at one end and radiating along the axis of the helix. A ground plane at the driven end makes the radiation unidirectional from the far (open) end.

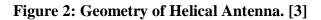




The benefits of this helix antenna *axial mode* or *end-fire* helix are it has a wide bandwidth, is easily constructed, and has real input impedance.

The parameters of the helix antenna shown in figure 2 are defined Next Page.





- D Diameter of a turn on the helix antenna.
- C Circumference of a turn on the helix antenna (*C*=pi\**D*).
- S Vertical separation between turns for helical antenna.

•  $\alpha$  - pitch angle, which controls how far the helix antenna grows in the z-direction per turn, and is given by

$$\alpha = \tan^{-1} \frac{S}{C}$$

- N Number of turns on the helix antenna.
- H Total height of helix antenna, *H*=*NS*.

The antenna in Figure 2 is a left handed helix antenna, because if you curl your fingers on your left hand around the helix your thumb would point up (also, the waves emitted from this helix antenna are Left Hand Circularly Polarized). If the helix antenna was wound the other way, it would be a right handed helical antenna.

The radiation pattern will be maximum in the +z direction (along the helical axis in Figure 1). The design of helical antennas is primarily based on empirical results, and the fundamental equations will be presented here.

Helix antennas of at least 3 turns will have close to circular polarization in the +z direction when the circumference C is close to a wavelength:

$$\frac{3\lambda}{4} \le C \le \frac{4\lambda}{3}$$

Once the circumference C is chosen, the inequalities above roughly determine the operating bandwidth of the helix antenna. For instance, if C=0.5 meters, then the highest frequency of operation will be given by the smallest wavelength that fits into the above equation, or =0.75C=0.375 meters, which corresponds to a frequency of 800 MHz. The lowest frequency of operation will be given by the largest wavelength that fits into the above equation, or =1.333C=0.667 meters, which corresponds to a frequency of 450 MHz. Hence, the *fractional BW*\* is 56%, which is true of axial helical antennas in general.

The fractional bandwidth of an antenna is a measure of how wideband the antenna is. If the antenna operates at center frequency fc between lower frequency f1 and upper frequency f2 (where fc=(f1+f2)/2), then the fractional bandwidth FBW is given by:

$$FBW = \frac{f_2 - f_1}{f_c}$$

The fractional bandwidth varies between 0 and 2, and is often quoted as a percentage (between 0% and 200%). The higher the percentage, the wider the bandwidth.

Wideband antennas typically have a Fractional Bandwidth of 20% or more. Antennas with a FBW of greater than 50% are referred to as ultra-wideband antennas; this means that helical antenna is an ultra-wideband antenna.

The helix antenna is a travelling wave antenna, which means the current travels along the antenna and the phase varies continuously. In addition, the input impedance is primarily real and can be approximated in Ohms by:

$$Z_{in} = 140 \frac{C}{\lambda}$$

The helix antenna functions well for pitch angles ( $\alpha$ ) between 12 and 14 degrees. Typically, the pitch angle is taken as 13 degrees.

The normalized radiation pattern for the E-field components is given by:

$$E_{\theta} \propto E_{\phi} \propto \sin \frac{\pi}{2N} \cos \theta \frac{\sin \frac{N\Omega}{2}}{\sin(\Omega/2)}$$
$$\Omega = kS(\cos \theta - 1) - \pi (2 + 1/N)$$

For circular polarization, the orthogonal components of the E-field must be 90 degrees out of phase. This occurs in directions near the axis (z-axis in Figure 1) of the helix. The axial ratio for helix antennas decreases as the number of loops N is added, and can be approximated by:

$$AR = \frac{2N+1}{2N}$$

The axial ratio is the ratio of orthogonal components of an E-field. A circularly polarized field is made up of two orthogonal E-field components of equal amplitude (and 90 degrees out of phase). Because the components are equal magnitude, the axial ratio is 1 (or 0 dB).

The axial ratio for an ellipse is larger than 1 (>0 dB). The axial ratio for pure linear polarization is infinite, because one of the orthogonal components of the field is zero.

Axial ratios are often quoted for antennas in which the desired polarization is circular. The ideal value of the axial ratio for circularly polarized fields is 0 dB. In addition, the axial ratio tends to degrade away from the mainbeam of an antenna, so the axial ratio may be indicated in a spec sheet (data sheet) for an antenna as follows: "Axial Ratio: <3 dB for +-30 degrees from mainbeam". This indicates that the deviation from circular polarization is less than 3 dB over the specified angular range.

The gain of the helix antenna can be approximated by:

$$G = \frac{6.2C^2 NS}{\lambda^3} = \frac{6.2C^2 NSf^3}{c^3}$$

In the above, c is the speed of light. Note that for a given helix geometry (specified in terms of C, S, N), the gain increases with frequency. For an N=10 turn helix, that has a 0.5 meter circumference as above, and pitch angle of 13 degrees (giving S=0.13 meters), the gain is 8.3 (9.2 dB).

For the same example helix antenna, the pattern is shown in Figure 3:

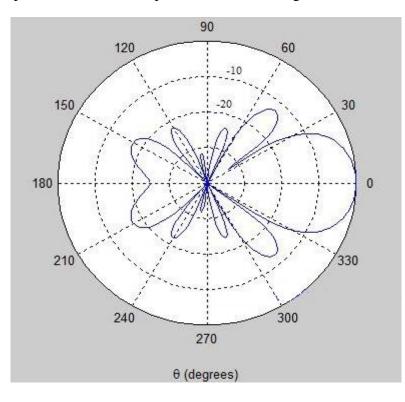


Figure 3: Radiation Pattern Helical Antenna. [3]

The Half-Power Beamwidth for helical antennas can be approximated (in degrees) by:

$$HPBW = \frac{65\lambda}{C\sqrt{\frac{NS}{\lambda}}}$$

The Beamwidth between nulls is approximately:

$$FNBW(degrees) \simeq \frac{115\lambda^{3/2}}{C\sqrt{NS}}$$

. .

### **CONCLUTIONS:**

- Helical antennas have long been popular in applications from VHF to microwaves requiring circular polarization.
- A helical antenna is an antenna consisting of a conducting wire wound in the form of a helix.
- In the *normal mode* or *broadside* helix, the dimensions of the helix (the diameter and the pitch) are small compared with the wavelength. The antenna acts similarly to an electrically short dipole or monopole.
- In the *axial mode* or *end-fire* helix, the dimensions of the helix are comparable to a wavelength. The antenna functions as a directional antenna radiating a beam off the ends of the helix, along the antenna's axis. It radiates circularly polarized radio waves.
- The benefits of this helix antenna *axial mode* or *end-fire* helix are it has a wide bandwidth, is easily constructed, and has real input impedance.
- The helix antenna is a travelling wave antenna, which means the current travels along the antenna and the phase varies continuously.
- The *fractional Bandwidth* of helical antennas is 56%.
- One limitation of helical antennas is that the usefulness of the circular polarization is limited since it cannot be easily reversed to the other sense, left-handed to right-handed or vice-versa

## REFERENCES

1. Helical Feed Antennas Paul Wade W1GHZ.

2. http://en.wikipedia.org/wiki/Helical\_antenna

3. http://www.antenna-theory.com/antennas/travelling/helix.php

4. Antenna Theory: Analysis and Design, Second Edition, Constantine A. Balanis, Chapter 10 Section 10.3.

## Helical Antennas

Supervisor:

Dr. Omar Saraereh

Written By:

Bahaa Ishaq Radi 833150

Wael Malkawi 833149

# Contents

• Overview of Helical Antenna

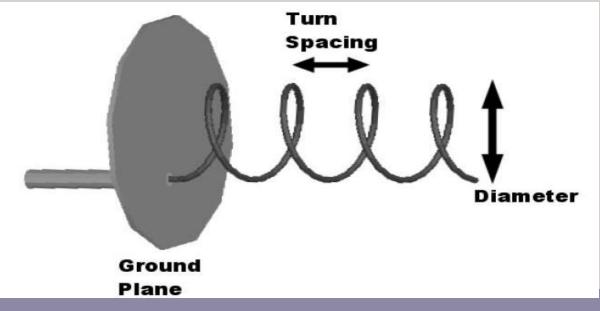
•Geometry and Operation of Helical Antenna

• Impedance, Gain, and Radiation Pattern

•Result of Calculating the Gain and Plot of Radiation Pattern

# Overview:

A helical antenna is an antenna consisting of a conducting wire wound in the form of a helix. In most cases, helical antennas are mounted over a ground plane. The feed line is connected between the bottom of the helix and the ground plane. Helical antennas can operate in one of two principal modes: normal mode or axial mode.



## Normal mode or Broadside helix

In the *normal mode* or *broadside* helix, the dimensions of the helix (the diameter and the pitch) are small compared with the wavelength. The antenna acts similarly to an electrically short dipole or monopole, and the radiation pattern, similar to these antennas is omnidirectional, with maximum radiation at right angles to the helix axis. The radiation is linearly polarized parallel to the helix axis.

## Axial mode or End-fire helix

In the *axial mode* or *end-fire* helix, the dimensions of the helix are comparable to a wavelength. The antenna functions as a directional antenna radiating a beam off the ends of the helix, along the antenna's axis. It radiates circularly polarized radio waves.

The benefits of this helix antenna *axial mode* or *end-fire* helix are it has a wide bandwidth, is easily constructed, and has real input impedance.

## Geometry and Operation

D - Diameter of a turn on the helix antenna.
C - Circumference of a turn on the helix antenna (*C*=pi\**D*).

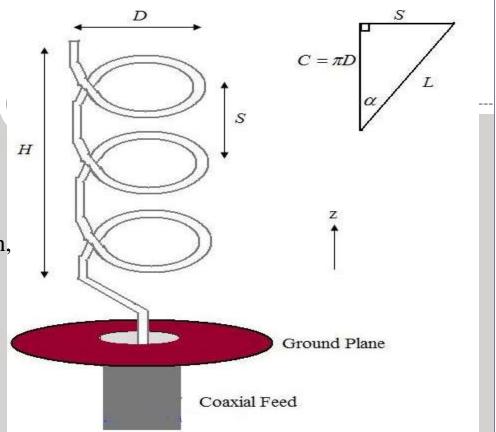
• S - Vertical separation between turns for helical antenna.

 $\cdot^{\alpha}$ - pitch angle, which controls how far the helix antenna grows in the z-direction per turn, and is given by

 $\alpha = \tan^{-1}\frac{S}{C}$ 

N - Number of turns on the helix antenna.

H - Total height of helix antenna, H=NS.



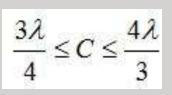
Geometry and Operation

The radiation pattern will be maximum in the +z direction (along the helical axis).

The design of helical antennas is primarily based on empirical results, and the fundamental equations will be presented here.

Helix antennas of at least 3 turns will have close to circular polarization in the +z direction when the

circumference C is close to a wavelength:



The helix antenna is a travelling wave antenna, which means the current travels along the antenna and the phase varies continuously.

In addition, the input impedance is primarily real and can be approximated in Ohms by:

$$Z_{in} = 140 \frac{C}{\lambda}$$

The helix antenna functions well for pitch angles ( $\alpha$ ) between 12 and 14 degrees.

Typically, the pitch angle is taken as 13 degrees.

The normalized radiation pattern for the E-field components is given by:

$$E_{\theta} \propto E_{\phi} \propto \sin \frac{\pi}{2N} \cos \theta \frac{\sin \frac{N\Omega}{2}}{\sin(\Omega/2)}$$
$$\Omega = kS(\cos \theta - 1) - \pi(2 + 1/N)$$

For circular polarization, the orthogonal components of the E-field must be 90 degrees out of phase.

This occurs in directions near the axis (z-axis in Figure 1) of the helix. The axial ratio for helix antennas decreases as the number of loops N is added, and can be approximated by:

$$AR = \frac{2N+1}{2N}$$

The axial ratio is the ratio of orthogonal components of an E-field. A circularly polarized field is made up of two orthogonal E-field components of equal amplitude (and 90 degrees out of phase).

Because the components are equal magnitude, the axial ratio is 1 (or 0 dB).

The gain of the helix antenna can be approximated by:

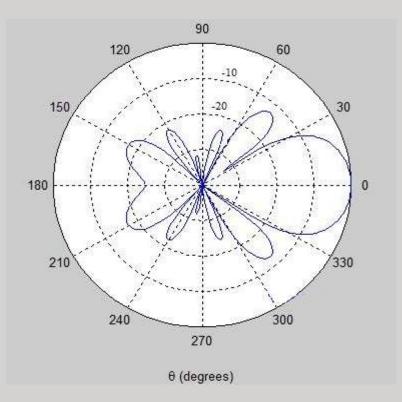
$$G = \frac{6.2C^2 NS}{\lambda^3} = \frac{6.2C^2 NSf^3}{c^3}$$

In the above, c is the speed of light.

For an N=10 turn helix, that has a 0.5 meter Circumference as above, and pitch angle of 13 degrees

(giving S=0.13 meters), the gain is 8.3 (9.2 dB).

For the same example helix antenna, the pattern is shown in the figure :



The Half-Power Beamwidth for helical antennas can be approximated (in degrees) by:

$$HPBW = \frac{65\lambda}{C\sqrt{\frac{NS}{\lambda}}}$$

The Beamwidth between nulls is approximately:

$$FNBW(degrees) \simeq \frac{115\lambda^{3/2}}{C\sqrt{NS}}$$

