

The Hashemite University Faculty of Engineering, Mechatronics Engineering Robotics Course Syllabus

Course Title:	Robotics	Cours	se Number:	110405442
Department:	Mechatronics Engineering	g Desig	Designation: Compulsory	
Prerequisite(s):	110405331 and 110406260			
Instructors:	Dr. Mohammed Abu mallouh Instructor's Office: 3129			
Instructor's email:	mmallouh@hu.edu.jo			
Office Hours:	Sunday @ 2:30-3:30 pm			
	Also other time can be arranged			
Time:	3:30-4:45 Every day except Thursday Class Room: Online MS teams			
Course description:	The purpose of this course is to introduce the student to the basics of modeling, design, planning and control of robotic systems.			
Textbook(s):	John Craig, Introduction to Robotics: Mechanics and Control, Addison Wesley Publishing Company, Inc., 3ed edition.			
Other required material:	 L. Sciavicco and B. Siciliano, Modeling and Control of Robot Manipulators, Springer, 2000. Mark W. Spong, Seth Hutchinson and M. Vidyasagar, Robot Modeling and Control, John Wiley & Sons, Inc., 2006. Paul, R., P., Robot Manipulator, MIT Press. 1981. Wolfram Stadler, Analytical Robotics and Mechatronics, McGraw-Hill Companies, 1995. H. Asada and E. Slotine, Robot Analysis and Control, Wiley-Interscience, 1986. 			
Topics covered:	 Introduction Spatial descriptions and transformations Manipulator kinematics Inverse manipulator kinematics Jacobians: Velocities and static forces Manipulator dynamics 			
Grading Plan:	Midterm exam 40 Points		15-8-2021, Sunday @ 3:30-4:45	
	Others (HW, Quizzes)	20 Points	TBD	
	Final Exam: 40 Points		Will be announced by the registrar	
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Major Topics Covered and	Schedule in Weeks:			
ropic		# Weeks	Weeks # hours	
1. Ch1 Introduction			3	
2. Ch2 Spatial descriptions and transformations			9	
3. Ch3 Manipulator kinematics			9	
4. Ch4 Inverse manipulator kinematics			9	
5. Ch5 Jacobians: Velocities and static forces			9	
6. Ch6 Manipulator dynamics			9	
Total			48	
Course Policy				
Attendance is mandatory and abs	sence is allowed up to 15% lea	ctures		
		Mohammed Abu Ilouh	Date:	2/7/2021